

# Lecture 12

## Unification. Resolution

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- ▶ For practical purposes, given a finite set of ground formulae, one can rename the distinct ground atoms by distinct propositional formulae and thus answer the question of unsatisfiability by **propositional resolution**.  
See [Crăciun, 2010] for details on propositional resolution.
- ▶ However, this approach is not practical: there is no indication how to find the finite set of ground formulae: the set of possible ground instantiations is both unbounded and unstructured.

- ▶ A **substitution** of terms for variables is a set:

$$\{x_1 \leftarrow t_1, \dots, x_n \leftarrow t_n\}$$

where, for  $i = 1 \dots n$ ,  $x_i$  are distinct variables,  $t_i$  are terms such that  $x_i$  and  $t_i$  are distinct. Substitutions will be denoted by lowercase greek letters ( $\lambda, \theta, \delta, \sigma$ ). The **empty** substitution is denoted by  $\epsilon$ .

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- ▶ Let  $E$  be an expression,  $\theta = \{x_1 \leftarrow t_1, \dots, x_n \leftarrow t_n\}$ . An **instance of  $E$**  (or the result of applying  $\theta$  to  $E$ ),  $E\theta$  is the expression obtained by **simultaneously** replacing every occurrence of  $x_i$  in  $E$  by  $t_i$ .

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- ▶ **Example:** let  $E = p(x) \vee q(f(y))$ ,  $\theta = \{x \leftarrow y, y \leftarrow f(a)\}$ .  
Then

$$E\theta = p(y) \vee q(f(f(a))).$$



- Let  $\theta = \{x_1 \leftarrow t_1, \dots, x_n \leftarrow t_n\}$  and  $\sigma = \{y_1 \leftarrow s_1, \dots, y_k \leftarrow s_k\}$  be substitutions. Let  $X, Y$  be the sets of variables from  $\theta$  and  $\sigma$ , respectively. The **composition of  $\theta$  and  $\sigma$** ,  $\theta\sigma$  is the substitution:

$$\theta\sigma = \{x_i \leftarrow t_i\sigma \mid x_i \in X, x_i \neq t_i\sigma\} \cup \{y_j \leftarrow s_j \mid y_j \in Y, y_j \notin X\},$$

in other words, apply the substitution  $\sigma$  to the terms  $t_i$  (provided that the resulting substitution does not collapse into  $x_i \leftarrow x_i$ ) then append the substitutions from  $\sigma$  whose variables do not appear already in  $\theta$ .

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- **Example: let**

$$\begin{aligned}\theta &= \{x \leftarrow f(y), y \leftarrow f(a), z \leftarrow u\}, \\ \sigma &= \{y \leftarrow g(a), u \leftarrow z, v \leftarrow f(f(a))\},\end{aligned}$$

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applied to both the literals will make them identical (will “unify” them),

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- ▶ Given a set of literals, a **unifier** is a substitution that makes the atoms of the set identical. A **most general unifier (mgu)** is a unifier  $\mu$  such that any other unifier  $\theta$  can be obtained from  $\mu$  by a further substitution  $\lambda$  such that  $\theta = \mu\lambda$ .



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- ▶ Note that not all literals are unifiable: if the predicate symbols are different, the literals cannot be unified. Also, consider the case of  $p(x)$  and  $p(f(x))$ . Since the substitution of the variable  $x$  has to be done in the same time, the terms  $x$  and  $f(x)$  cannot be made identical, and the unification will fail.

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A set of equations in solved form defines a substitution in a natural way by turning each equation  $x_i = t_i$  into an element of the substitution,  $x_i \leftarrow t_i$ .

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3. Let  $t' = t''$  be an equation where  $t'$ ,  $t''$  are not variables. If the outermost (function) symbol of  $t'$  and  $t''$  are not identical, terminate and answer “not unifiable”. Otherwise, if  $t'$  is of the form  $f(t'_1, \dots, t'_k)$  and  $t''$  is of the form  $f(t''_1, \dots, t''_k)$ , replace the equation  $f(t'_1, \dots, t'_k) = f(t''_1, \dots, t''_k)$  by the  $k$  equations

$$t'_1 = t''_1, \dots, t'_k = t''_k.$$

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4. Let  $x = t$  a term equation such that  $x$  has another occurrence in the set of term equations. If  $x$  occurs in  $t$  (occurs check!), terminate and answer “not unifiable”. Otherwise, transform the equation set by replacing each occurrence of  $x$  in other equations by  $t$ .

## Example (Unification, from [Ben-Ari, 2001])

Consider the following two equations:

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- ▶ Apply rule 4 on the second equation to replace the other occurrences of  $x$ :

$$\begin{aligned}g(z) &= g(y) \\ x &= g(z) \\ h(g(z)) &= w \\ y &= z.\end{aligned}$$



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- ▶ Transform the second equation by rule 1:

$$\begin{aligned}x &= g(z) \\w &= h(g(z)) \\y &= z.\end{aligned}$$

## Example (Unification, from [Ben-Ari, 2001])

- ▶ The algorithm terminates successfully. The resulting substitution

$$\{x \leftarrow g(z), w \leftarrow h(g(z)), y \leftarrow z\}$$

is the most general unifier of the initial set of equations.

### Theorem (Correctness of the unification algorithm)

*The unification algorithm terminates. If the algorithm terminates with the answer “not unifiable”, there is no unifier for the set of term equations. If it terminates successfully, the resulting set of equations is in solved form and it defines an mgu*

$$\mu = \{x_1 \leftarrow t_1, \dots, x_n \leftarrow t_n\}$$

*of the set of equations*

**Proof.**

See [Ben-Ari, 2001], pp. 158.

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- ▶ It turns out that a practical version of resolution is possible, using unification.
- ▶ Recall the notions of literal, clause, clause sets introduced in the previous lecture.
- ▶ **Notation.** Let  $L$  be a literal. We denote with  $L^c$  the complementary literal (i.e.  $L$  and  $L^c$  are opposite, one is the negation of the other).



## Definition (General resolution step)

Let  $C_1, C_2$  be clauses *with no variables in common*. Let  $L_1 \in C_1$  and  $L_2 \in C_2$  be literals in the clauses such that  $L_1$  and  $L_2^c$  can be unified by a mgu  $\sigma$ . Then  $C_1$  and  $C_2$  are said to be **clashing clauses**, that **clash on the literals**  $L_1$  and  $L_2$ , and **resolvent of  $C_1$  and  $C_2$**  is the clause:

$$\text{Res}(C_1, C_2) = (C_1\sigma - L_1\sigma) \cup (C_2\sigma - L_2\sigma).$$

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$L_1 = p(f(x), g(y))$  and  $L_2^c = p(f(f(a)), g(z))$  can be unified with the mgu  $\{x \leftarrow f(a), y \leftarrow z\}$  and the resolvent of the clauses is:

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- ▶ Note that the requirement for clauses to have no variables in common does not impose any real restrictions on the clause set. Remember that clauses are implicitly universally quantified, so changing the name of a variable does not change the meaning of the clause set.

# General Resolution Procedure.

**INPUT:** A set of clauses  $S$ .

Note that the algorithm above may not terminate, it is not a decision procedure (indeed that would not be expected since first order predicate logic is undecidable). The reason for nontermination is the existence of infinite models.

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  - ▶ **Otherwise,**  $S_{i+1} = S_i \cup \{C\}$ .

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- ▶ Repeat
  - ▶ **Choose**  $C_1, C_2 \in S_i$  clashing clauses and let  $C = Res(C_1, C_2)$ .
  - ▶ If  $C = \emptyset$  terminate with the answer “not satisfiable”.
  - ▶ Otherwise,  $S_{i+1} = S_i \cup \{C\}$ .
- ▶ **until**  $S_{i+1} = S_i$

Note that the algorithm above may not terminate, it is not a decision procedure (indeed that would not be expected since first order predicate logic is undecidable). The reason for nontermination is the existence of infinite models.

## General Resolution Procedure.

**INPUT:** A set of clauses  $S$ .

**OUTPUT:**  $S$  is satisfiable or  $S$  is not satisfiable. Also the algorithm may not terminate.

- ▶ Start with  $S_0 = S$ .
- ▶ Repeat
  - ▶ **Choose**  $C_1, C_2 \in S_i$  clashing clauses and let  $C = Res(C_1, C_2)$ .
  - ▶ If  $C = \emptyset$  terminate with the answer “not satisfiable”.
  - ▶ Otherwise,  $S_{i+1} = S_i \cup \{C\}$ .
- ▶ until  $S_{i+1} = S_i$
- ▶ **Return** “satisfiable”.

Note that the algorithm above may not terminate, it is not a decision procedure (indeed that would not be expected since first order predicate logic is undecidable). The reason for nontermination is the existence of infinite models.

## Example (Resolution refutation, from [Ben-Ari, 2001])

1.  $\neg p(x) \vee q(x) \vee r(x, f(x))$
2.  $\neg p(x) \vee q(x) \vee s(f(x))$
3.  $t(a)$
4.  $p(a)$
5.  $\neg r(a, y) \vee t(y)$
6.  $\neg t(x) \vee \neg q(x)$
7.  $\neg t(x) \vee \neg s(x)$
  
8.  $\neg q(a)$   $x \leftarrow a$  3, 6
9.  $q(a) \vee s(f(a))$   $x \leftarrow a$  2, 4
10.  $s(f(a))$  8, 9
11.  $q(a) \vee r(a, f(a))$   $x \leftarrow a$  1, 4
12.  $r(a, f(a))$  8, 11
13.  $t(f(a))$   $y \leftarrow f(a)$  5, 12
14.  $\neg s(f(a))$   $x \leftarrow f(a)$  7, 13
15.  $\emptyset$  10, 14



## Example (Resolution refutation with variable renaming, from [Ben-Ari, 2001])

First four clauses represent the initial clause set.

1.  $\neg p(x, y) \vee p(y, x)$
2.  $\neg p(x, y) \vee \neg p(y, z) \vee p(x, z)$
3.  $p(x, f(x))$
4.  $p(x, x)$
- 3'.  $p(x', f(x'))$  Rename 3.
5.  $p(f(x), x)$   $\sigma_1 = \{y \leftarrow f(x), x' \leftarrow x\} 1, 3'$
- 3''.  $p(x'', f(x''))$  Rename 3
6.  $\neg p(f(x), z) \vee p(x, z)$   $\sigma_2 = \{y \leftarrow f(x), x'' \leftarrow x\} 2, 3''$
- 5'''.  $p(f(x'''), x''')$  Rename 5
7.  $p(x, x)$   $\sigma_3 = \{z \leftarrow x, x''' \leftarrow x\} 6, 5'''$
- 4'''.  $\neg p(x''', x''')$  Rename 4
8.  $\emptyset$   $\sigma_4 = \{x'''' \leftarrow x\} 7, 4'''$

Resolution refutation with variable renaming, from [Ben-Ari, 2001].

- ▶ The substitution resulting from composing all intermediary substitutions:

$$\sigma = \sigma_1\sigma_2\sigma_3\sigma_4 =$$

$$\{y \leftarrow f(x), z \leftarrow x, x' \leftarrow x, x'' \leftarrow x, x''' \leftarrow x, x'''' \leftarrow x\}$$

- ▶ Restricted to the variables from the initial set, the resulting substitution is:

$$\sigma = \{y \leftarrow f(x), z \leftarrow x\}$$

## Theorem (Soundness of substitution)

## Theorem (Completeness of substitution)

*If a set of clauses is unsatisfiable, then the empty clause  $\emptyset$  can be derived by the resolution procedure.*

- ▶ For details on how the proofs of these theorems, see [Ben-Ari, 2001].

## Theorem (Soundness of substitution)

*If the unsatisfiable clause  $\emptyset$  is derived during the general resolution procedure, then the set of clauses is unsatisfiable.*

## Theorem (Completeness of substitution)

*If a set of clauses is unsatisfiable, then the empty clause  $\emptyset$  can be derived by the resolution procedure.*

- ▶ For details on how the proofs of these theorems, see [Ben-Ari, 2001].

## Some remarks on the resolution procedure

- ▶ Note that the resolution procedure is nondeterministic: which clashing clause to choose and which clashing literals to resolve on is not specified.

## Some remarks on the resolution procedure

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## Some remarks on the resolution procedure

- ▶ Note that the resolution procedure is nondeterministic: which clashing clause to choose and which clashing literals to resolve on is not specified.
- ▶ Good choices will lead to the result quickly, while bad choices may lead to the algorithm not terminating.
- ▶ The completeness theorem says that if the clause set is unsatisfiable a resolution refutation (generation of the empty clause) exists, i.e. that which uses good choices. Variants with bad choices may miss the solution.

- ▶ Read: Chapter 7, sections 7.5-7.8 of [Ben-Ari, 2001].
- ▶ Items of interest:
  - ▶ Ground resolution, impracticality of ground resolution (reasons).
  - ▶ Substitutions: compositions of substitutions, unifiers, most general unifiers.
  - ▶ Unification procedure.
  - ▶ General resolution, completeness of resolution (no proof).



- ▶ Read: Chapter 7, sections 7.1-7.4 of [Ben-Ari, 2001].
- ▶ Items of interest (no proofs required):
  - ▶ Predicate logic language: syntax, semantics(interpretation, model).
  - ▶ Herbrand's universe, Herbrand base, Herbrand interpretation
  - ▶ Herbrand's theorem, the significance of Herbrand's theorem.
  - ▶ Clausal form of first order formulae: Skolemization (Skolem constants, Skolem functions), transformation algorithm.



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