## **ARTIFICIAL INTELLIGENCE**

## LECTURE 10 (draft)

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#### INTRODUCTION

• The content of this lecture is based on chapter 18 from [RN].

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#### Learning

- Based on the type of feedback available, learning is:
  - Supervised
  - Unsupervised
  - Reinforcement learning
- Supervised learning involves learning a function from examples of it's inputs and outputs. E.g. interpolation
- Unsupervised learning involves learning patterns in the input when no specific output values are supplied.
- Reinforcement learning in which the learning agent learns from reinforcements (rewards)

# Knowledge representation (KR)

- KR plays an important role in determining how the learning algorithm works[RN651]:
  - linear weighted polynomials for utility functions in game-playing programs;
  - propositional and first-order logical sentences for all of the cornponents in a logical agent;
  - and probabilistic descriptions such as Bayesian networks for the inferential components of a decisiontheoretic agent.
- Availability of prior knowledge:
  - No prior knowledge and the agent learns from his own experience
  - Existence of background knowledge

#### • Inductive learning:

- given a collection of examples *f*, return a function *h* that approximates *f*
- *h* is called a hypothesis. A good hypothesis will predict unseen examples correctly.
- *H* is called a **hypothesis space** if it contains all the hypotheses we will consider. E.g. the set of polynomials of degree at most *k*
- A **consistent hypothesis** is one that agrees with all the data
- We say that a learning problem is **realizable** if the hypothesis space contains the true function; otherwise, it is **unrealizable**. E.g. if the correct function is a sinusoidal, then the polynomials cannot represent it correctly
- Usually we cannot tell if a problem is realizable because we do not know the function. A solution is to use prior knowledge to derive a hypothesis space in which we know the true function must lie

# LEARNING DECISION TREES

- A decision tree takes as input **objects** described by a **set of attributes** and gives as an output a **decision**, the predicted output value for the input.
- Attributes and output values can be:
  - discrete
  - continuous
- The learning of:
  - a discrete-valued function is called classification learning
  - a continuous function is called **regression**.
- A decision reaches a conclusion by performing a set of tests.
- Each internal node in the tree corresponds to a test of the value of one of the properties, and the branches from the node are labeled with the possible values of the test.

#### DECISION TREE [R18-14]



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• More commands for debugging [GR]

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# EXAMPLE EXPERT SYSTEM

- <u>https://web.archive.org/web/20130130102710/http://www.cs.trinity</u> <u>.edu/~yzhang/teaching/spring2011/CSCI3344/projects/instruction/</u> <u>cat.clp</u>
- The original location of the file is: <u>http://www.cs.trinity.edu/~yzhang/teaching/sprin</u> <u>g2011/CSCI3344/projects/instruction/cat.clp</u>



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